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VCE[®] Specialist Mathematics

Practice Written Examination 2

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Solution Pathway

Below are sample answers and solutions. Please consider the merit of alternative responses.

Specialist Mathematics Examination 2: Marking Scheme

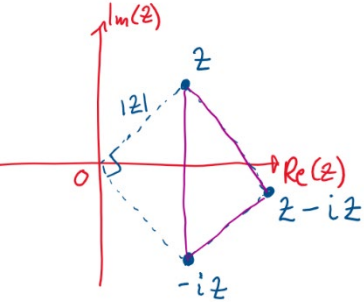
SECTION A: Multiple-Choice Questions – Answers

1.	C	5.	C	9.	A	13.	C	17.	C
2.	B	6.	D	10.	B	14.	D	18.	D
3.	A	7.	D	11.	C	15.	A	19.	C
4.	D	8.	B	12.	D	16.	B	20.	A

SECTION A: Multiple-Choice Questions – Solutions

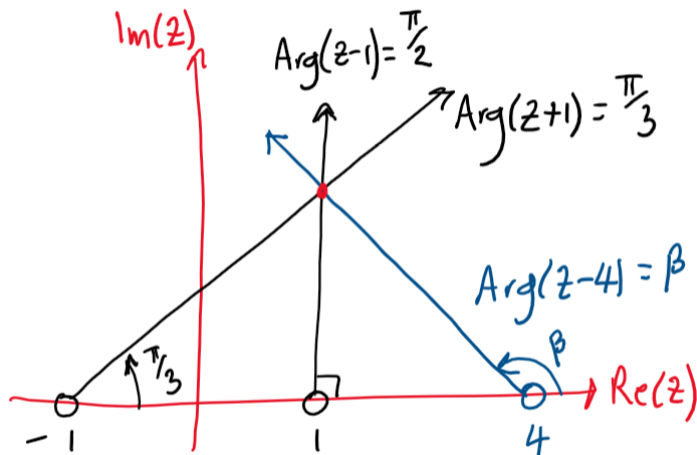
Q 1	<p>To prove that if $n^2 + 6n + 5$ is even then n is odd, it is assumed for the sake of contradiction that $n^2 + 6n + 5$ is even and n is even.</p> $P \Rightarrow Q$ $P \wedge \neg Q$	C
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<p>Q 2</p> <ul style="list-style-type: none"> $x = 6$ is a vertical asymptote therefore $x = 6$ is a root of $ax^2 + b x + c$: $36a + 6b + c = 0 \quad \dots (1)$ Let $g(x) = \frac{x^3 - 1}{ax^2 + bx + c}$ and $f(x) = \frac{ x ^3 - 1}{ax^2 + b x + c} = g(x)$ <p>From a CAS: $g(x) = \frac{1}{a}x - \frac{b}{a^2} + \frac{\text{Linear}}{ax^2 + bx + c}$</p> <p>Therefore $y = g(x)$ has an oblique asymptote $y = \frac{1}{a}x - \frac{b}{a^2}$</p> <ul style="list-style-type: none"> Case 1: $x \geq 0$: $f(x) = g(x)$ therefore $y = \frac{1}{a}x - \frac{b}{a^2}$ is a diagonal asymptote of $y = f(x)$. <p>Compare $y = \frac{1}{a}x - \frac{b}{a^2}$ with $y = -2x + 14$:</p> $\frac{1}{a} = -2 \Rightarrow a = -\frac{1}{2}. \quad -\frac{b}{a^2} = 14 \Rightarrow b = -14a^2 = -\frac{7}{2}$ <p>Substitute $a = -\frac{1}{2}$ and $b = -\frac{7}{2}$ into (1): $c = 39$. No corresponding option.</p> <ul style="list-style-type: none"> Case 2: $x < 0$: $f(x) = g(-x)$ therefore $y = -\frac{1}{a}x - \frac{b}{a^2}$ is a diagonal asymptote of $y = f(x)$ <p>Compare $y = -\frac{1}{a}x - \frac{b}{a^2}$ with $y = -2x + 14$:</p> $-\frac{1}{a} = -2 \Rightarrow a = \frac{1}{2}. \quad -\frac{b}{a^2} = 14 \Rightarrow b = -14a^2 = -\frac{7}{2}$ <p>Substitute $a = \frac{1}{2}$ and $b = -\frac{7}{2}$ into (1): $c = 3$. Option B.</p> <p>Discussion of Case 2:</p> <p>It follows that $g(x) = \frac{x^3 - 1}{\frac{1}{2}x^2 - \frac{7}{2}x + 3} = \frac{2(x-1)(x^2 + x + 1)}{(x-1)(x-6)} = \frac{2(x^2 + x + 1)}{x-6}, x \neq 1$</p> <p>Therefore $y = g(x)$ has a 'hole' at $x = 1$.</p>	B
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<p>Q 3</p>	<p>Horizontal asymptotes: $y = a - b^2 \left(\frac{\pi}{2} \right)$ and $y = a - b^2 \left(-\frac{\pi}{2} \right) = a + b^2 \left(\frac{\pi}{2} \right)$.</p> <p>It is therefore required that either:</p> <p>Case 1: $a - b^2 \left(\frac{\pi}{2} \right) \geq 0$ and $a > 0$ therefore $b^2 \leq \frac{2a}{\pi}$ and $a > 0$</p> <p>or</p> <p>Case 2: $a + b^2 \left(\frac{\pi}{2} \right) \leq 0$ and $a < 0$ therefore $b^2 \leq -\frac{2a}{\pi}$ and $a < 0$</p> <p>Both cases are equivalent to $b^2 \leq \left \frac{2a}{\pi} \right$</p>	<p>A</p>
<p>Q 4</p>	<p>The geometric interpretation of $-iz$ is the rotation of z by 90° in a clockwise direction. Therefore the area of the triangle is half the area of a square whose vertices are at $0, z, -iz, z - iz$:</p>  <p>By inspection the length of a side of the square is z therefore the area of the square is $z ^2$ therefore the area of the triangle is $\frac{1}{2} z ^2$.</p>	<p>D</p>

Q 5Let $z = x + iy$, $x, y \in \mathbb{R}$.

The rays $\text{Arg}(z+1) = \frac{\pi}{3}$, $\text{Arg}(z-1) = \frac{\pi}{2}$ and $\text{Arg}(z-4) = \beta$ intersect at the point where $x=1$:



The cartesian equation of $\text{Arg}(z+1) = \frac{\pi}{3}$ is $y = \sqrt{3}x + \sqrt{3}$, $x > -1$

Substitute $x=1$: $y = 2\sqrt{3}$

Therefore the rays $\text{Arg}(z+1) = \frac{\pi}{3}$, $\text{Arg}(z-1) = \frac{\pi}{2}$ and $\text{Arg}(z-4) = \beta$ intersect at $z = 1 + 2\sqrt{3}i$

Substitute $z = 1 + 2\sqrt{3}i$ into $\text{Arg}(z-4) = \beta$:

$$\beta = \text{Arg}(-3 + 2\sqrt{3}i) = \pi - \arctan\left(\frac{2\sqrt{3}}{3}\right)$$

C

Q 6

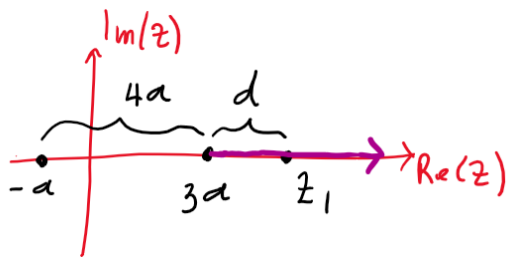
a is real therefore $3a$ and $-a$ lie on the real axis.

Geometric interpretation:

$|z+a|$ is the distance of z from $-a$, $|z-3a|$ is the distance of z from $3a$

The distance between $-a$ and $3a$ is $4a$

Let $z = z_1 \in R$ where $z_1 > 3a$. Let $|z_1 - 3a| = d \Rightarrow |z_1 + a| = 4a + d$:



Then $|z_1 + a| - |z_1 - 3a| = (4a + d) - d = 4a$

Therefore $|z+a| - |z-3a| = 4a$ defines a ray.

Discussion: By inspection, the equation of the ray is $y = 0, x \geq 3a$. The terminus of the ray has coordinates $(3a, 0)$ and is included as part of the ray.

Algebraic calculation:

Substitute $z = x + iy$, $x, y \in R$, into $|z+a| - |z-3a| = k$:

$$\sqrt{(x+a)^2 + y^2} - \sqrt{(x-3a)^2 + y^2} = k$$

$$\Rightarrow \sqrt{(x+a)^2 + y^2} = k + \sqrt{(x-3a)^2 + y^2}$$

$$\Rightarrow (x+a)^2 + y^2 = k^2 + (x-3a)^2 + y^2 + 2k\sqrt{(x-3a)^2 + y^2}$$

$$\Rightarrow 8ax - 8a^2 - k^2 = 2k\sqrt{(x-3a)^2 + y^2}$$

Note the implied restriction:

$$\text{RHS} \geq 0 \text{ therefore LHS} = 8ax - 8a^2 - k^2 \geq 0 \Rightarrow x \geq \frac{8a^2 + k^2}{8a}$$

$$\Rightarrow (8ax - 8a^2 - k^2)^2 = 4k^2((x-3a)^2 + y^2)$$

$$\Rightarrow (4a-k)(4a+k)(2x+k-2a)(2x-k-2a) = 4k^2y^2, \quad x \geq \frac{8a^2 + k^2}{8a}$$

If $k = 4a$ then a ray is obtained: $0 = 4k^2y^2 \Rightarrow y = 0, x \geq 3a$

D

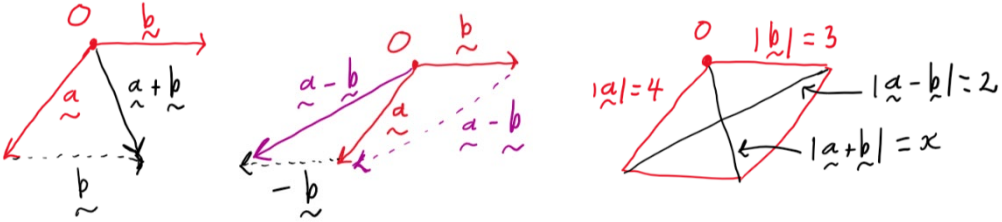
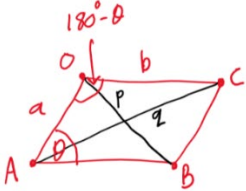
	<p>If $k > 4a$: $x > 3a$ and there is no solution since $LHS = (-ve)(+ve)(+ve)(+ve) < 0$ and $RHS > 0$</p>	
Q 7	<p>The pseudocode applies Euler's method to find an approximate solution to the differential equation $\frac{dx}{dt} = \frac{t^2 + 1}{x^3 + 1} = f(t, x)$ given that $t_0 = a$ and $x_0 = 3$</p> <p>The number of iterations is $n = 10$ therefore $t_{10} = b = 4$, the value of the step size is $\frac{b-a}{n} = \frac{4-a}{10}$ and $x_{10} = 3.504$ (output correct to three decimal places).</p> <p>Substitute the value of a in each option into the above data and execute Euler's Method on a CAS.</p>	D

Q 8	<p>$\frac{dm}{dt}$ = (rate at which salt enters the tank) – (rate at which salt leaves the tank).</p> <ul style="list-style-type: none"> • Rate at which salt enters the tank = (rate of inflow) (concentration of salt in inflow) = (5 litres per minute) (6 kg per litre) = 30 kg per minute. • Rate at which salt leaves the tank = (rate of outflow) (concentration of salt in outflow) = (7 litres per minute) (concentration of salt in outflow). • After t minutes have elapsed: Concentration of salt in outflow = $\frac{m}{V}$ <p>where V is the volume of solution in the tank after t minutes:</p> $V = (\text{initial volume}) + (\text{volume added after } t \text{ minutes via inflow})$ $\quad - (\text{volume removed after } t \text{ minutes via outflow})$ $= 90 \text{ litres} + 5t \text{ litres} - 7t \text{ litres} = 90 - 2t \text{ litres.}$ <p>Therefore: concentration of salt in outflow = $\frac{m}{V} = \frac{m}{90 - 2t}$ kg per litre.</p> <p>Therefore rate at which salt leaves the tank = (7 litres per minute) (concentration of salt in outflow)</p> $= (7) \left(\frac{m}{90 - 2t} \right) = \frac{7m}{90 - 2t} \text{ kg per minute}$ <p>$\frac{dm}{dt}$ = (rate at which salt enters the tank) – (rate at which salt leaves the tank)</p> $= (30) - \left(\frac{7m}{90 - 2t} \right) = 30 - \frac{7m}{90 - 2t}$	B
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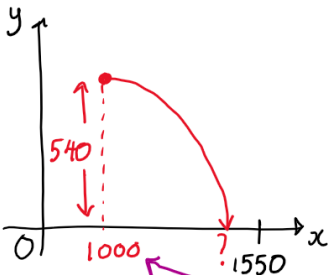
	<ul style="list-style-type: none"> Differential equation for the concentration c of salt in the tank at time t: $c = \frac{m}{V} = \frac{m}{90-2t} \Rightarrow m = c(90-2t)$ $\Rightarrow \frac{dm}{dt} = \frac{d}{dt}(c(90-2t)) = \frac{dc}{dt}(90-2t) + c(-2) = (90-2t)\frac{dc}{dt} - 2c$ <p style="text-align: center;"><small>Product Rule</small></p> <p>Substitute $\frac{dm}{dt} = 30 - \frac{7m}{90-2t}$:</p> $(90-2t)\frac{dc}{dt} - 2c = 30 - \frac{7c(90-2t)}{90-2t} \Rightarrow (90-2t)\frac{dc}{dt} = 30 - 5c$	
<p>Q 9</p>	<p>The value of $\frac{dy}{dx}$ at $t=2$ is required.</p> <p>When $t > \sqrt{3}$: $x(t) = \frac{ 3-t^2 }{t+1} = \frac{t^2-3}{t+1}$, $y(t) = -\frac{4}{t+2}$.</p> <p>Use a CAS to get the values of $\frac{dx}{dt}$ and $\frac{dy}{dt}$ when $t=2$:</p> $\frac{dy}{dx} = \frac{dy}{dt} \times \frac{dt}{dx} = \frac{9}{44} \text{ when } t=2$	<p>A</p>

Q 10	<p>Consider $J_n = \int \sec^n(x) dx$ and use integration by parts:</p> $\int u \frac{dv}{dx} dx = uv - \int v \frac{du}{dx} dx$ <p>Let $u = \sec^{n-2}(x)$</p> $\Rightarrow \frac{du}{dx} = (n-2)\sec(x)^{n-3} \sin(x) \sec^2(x) = (n-2)\sec(x)^{n-1} \sin(x)$ <p>Let $\frac{dv}{dx} = \sec^2(x) \Rightarrow v = \tan(x)$</p> $J_n = \underbrace{\sec^{n-2}(x)}_u \underbrace{\tan(x)}_v - \int \underbrace{\tan(x)}_v \underbrace{(n-2)\sec^{n-1}(x) \sin(x)}_{\frac{du}{dx}} dx$ $= \sec^{n-2}(x) \tan(x) - (n-2) \int \sin^2(x) \sec^n(x) dx$ $= \sec^{n-2}(x) \tan(x) - (n-2) \int (1 - \cos^2(x)) \sec^n(x) dx$ $= \sec^{n-2}(x) \tan(x) - (n-2) \left[\int \sec^n(x) dx - \int \sec^{n-2}(x) dx \right]$ $= \sec^{n-2}(x) \tan(x) - (n-2) [J_n - J_{n-2}]$ $= \sec^{n-2}(x) \tan(x) - (n-2)J_n + (n-2)J_{n-2}$ $\Rightarrow J_n = \frac{1}{n-1} \sec^{n-2}(x) \tan(x) + \frac{n-2}{n-1} J_{n-2} \quad (n \neq 1)$ $\Rightarrow I_n = \frac{1}{n-1} \left[\sec^{n-2}(x) \tan(x) \right]_0^{\frac{\pi}{3}} + \frac{n-2}{n-1} I_{n-2} = \frac{2^{n-2}}{n-1} \sqrt{3} + \frac{n-2}{n-1} I_{n-2}$	B
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<p>Q 11</p>	<p>The area of the surface generated by rotating the curve with equation $y = \tan^{-1}(x)$ about the line $x = 1$ from the points where $x = 2$ to $x = 4$ is equal to the surface generated by rotating the curve with equation $y = \tan^{-1}(x + 1)$ about the y-axis from the points where $x = 1$ to $x = 3$.</p> <p>Area of the surface generated by rotating the curve $y = f(x)$ about the y-axis:</p> $S = 2\pi \int_{y=a}^{y=b} x \sqrt{1 + \left(\frac{dx}{dy}\right)^2} dy$ <p>$y = \tan^{-1}(x + 1) \Rightarrow \tan(y) = x + 1 \Rightarrow x = \tan(y) - 1$</p> <p>$x = 1 \Rightarrow y = \tan^{-1}(2) . \quad x = 3 \Rightarrow y = \tan^{-1}(4)$</p> $S = 2\pi \int_{\tan^{-1}(2)}^{\tan^{-1}(4)} (\tan(y) - 1) \sqrt{1 + \sec^4(y)} dy$	<p>C</p>
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<p>Q 12</p>	<p>The vectors \vec{a} and \vec{b} form a parallelogram with pairs of opposite sides of length $\vec{a} = 4$ and $\vec{b} = 3$ and diagonals of length $\vec{a} - \vec{b} = 2$ and $\vec{a} + \vec{b} = x$:</p>  <p>For the parallelogram with pairs of opposite sides of length a and b and diagonals of length p and q: $p^2 + q^2 = 2(a^2 + b^2)$.</p>  <p> $\Delta OAB: p^2 = a^2 + b^2 - 2ab \cos(\theta)$ — ① $\Delta OAC: q^2 = a^2 + b^2 - 2ab \cos(180^\circ - \theta)$ $= a^2 + b^2 + 2ab \cos(\theta)$ — ② ① + ②: $p^2 + q^2 = 2(a^2 + b^2)$ </p> <p>$p^2 + q^2 = 2(a^2 + b^2) \Rightarrow 2^2 + x^2 = 2(4^2 + 3^2) \Rightarrow x = \vec{a} + \vec{b} = \sqrt{46}$</p>	<p>D</p>
<p>Q 13</p>	<p>Let the angle between \vec{a} and \vec{b} be θ:</p> <ul style="list-style-type: none"> $\vec{a} \cdot \vec{b} = 4 \Rightarrow \vec{a} \vec{b} \cos(\theta) = 4$. (1) $\vec{a} \times \vec{b} = 7 \Rightarrow \vec{a} \vec{b} \sin(\theta) = 7$. (2) <p>$\frac{(2)}{(1)}: \tan(\theta) = \frac{7}{4} \Rightarrow \theta \approx 60.3^\circ$</p>	<p>C</p>
<p>Q 14</p>	<p>$v = \frac{dx}{dt} = \tan^{-1}(x) \Rightarrow \frac{dt}{dx} = \frac{1}{\tan^{-1}(x)}$ and $x = 2$ when $t = 3$.</p> <p>The integral solution must be used: $t = \int_2^x \frac{1}{\tan^{-1}(w)} dw + 3$.</p>	<p>D</p>

	Substitute $x = 5$: $t = \int_2^5 \frac{1}{\tan^{-1}(w)} dw + 3 \approx 5.359$	
Q 15	<p>The acceleration of the object is constant therefore the straight line motion formulae for constant acceleration can be used:</p> <ul style="list-style-type: none"> • Motion after 10 seconds: Data: $u = 6 \text{ ms}^{-1}$, $v = -8 \text{ ms}^{-1}$, $t = 10$ seconds, $a = ?$ $v = u + at \Rightarrow -8 = 6 + a(10) \Rightarrow a = -1.4 \text{ ms}^{-2}$ • Motion after 12 seconds: Data: $u = 6 \text{ ms}^{-1}$, $t = 12$ seconds, $a = -1.4 \text{ ms}^{-2}$, $x = ?$ $x = ut + \frac{1}{2}at^2 = 6(12) + \frac{1}{2}(-1.4)(12)^2 = -28.8 \text{ m}$ <p>Therefore the distance is 28.8 metres.</p>	A

<p>Q 16</p> <ul style="list-style-type: none"> Time at which the aircraft drops the package: $540 = 600 - 3t \Rightarrow t = 20$ seconds. Initial conditions for the motion of the package: $\vec{r}_p(0) = \vec{r}(20) = 1000\vec{i} + 540\vec{j}, \quad \dot{\vec{r}}_p(0) = \dot{\vec{r}}(20) = 50\vec{i} - 3\vec{j}$ <p>Method 1:</p> <p>Solve $\ddot{\vec{r}}_p(t) = -9.8\vec{j}$ (since the air resistance acting on the package is negligible) subject to the above initial conditions (either using a CAS or 'by hand'):</p> $\vec{r}_p(t) = (1000 + 50t)\vec{i} + (540 - 3t - 4.9t^2)\vec{j}$ <p>Therefore $x_p(t) = 1000 + 50t$ and $y_p(t) = 540 - 3t - 4.9t^2$</p> <ul style="list-style-type: none"> Time at which the package lands: $y_p(t) = 540 - 3t - 4.9t^2 = 0 \quad (\text{and } t > 0) \Rightarrow t = 10.1962$ <ul style="list-style-type: none"> Horizontal distance of package from O: $x_p(10.1962) = 1000 + 50(10.1962) = 1509.81 \text{ m}$ <p>Method 2:</p>  <p>Initial horizontal distance from O: $x = vt = (50)(20) = 1000$</p> <ul style="list-style-type: none"> Acceleration of the package is constant therefore the straight line motion formulae for constant acceleration can be used: <table style="width: 100%; border: none;"> <tr> <td style="vertical-align: top; padding: 5px;"> <p>Horizontal motion ($\rightarrow +ve$):</p> <p>$u = 50 \text{ ms}^{-1}, a = 0 \text{ ms}^{-2}$</p> <p>$y = 540 \text{ m}$</p> <p>$t = ? \text{ 10.1962}, x = ?$</p> <p>$x = ut + \frac{1}{2}at^2 = (50)(10.1962) = 509.81$</p> </td> <td style="vertical-align: top; padding: 5px;"> <p>Vertical motion ($\downarrow +ve$):</p> <p>$u = 3 \text{ ms}^{-1}, a = 9.8 \text{ ms}^{-2}$,</p> <p>$t = ?$</p> <p>$y = ut + \frac{1}{2}at^2 \Rightarrow 540 = 3t + 4.9t^2$</p> </td> </tr> </table> <p>$\Rightarrow t \approx 10.1962$</p>	<p>Horizontal motion ($\rightarrow +ve$):</p> <p>$u = 50 \text{ ms}^{-1}, a = 0 \text{ ms}^{-2}$</p> <p>$y = 540 \text{ m}$</p> <p>$t = ? \text{ 10.1962}, x = ?$</p> <p>$x = ut + \frac{1}{2}at^2 = (50)(10.1962) = 509.81$</p>	<p>Vertical motion ($\downarrow +ve$):</p> <p>$u = 3 \text{ ms}^{-1}, a = 9.8 \text{ ms}^{-2}$,</p> <p>$t = ?$</p> <p>$y = ut + \frac{1}{2}at^2 \Rightarrow 540 = 3t + 4.9t^2$</p>	B
<p>Horizontal motion ($\rightarrow +ve$):</p> <p>$u = 50 \text{ ms}^{-1}, a = 0 \text{ ms}^{-2}$</p> <p>$y = 540 \text{ m}$</p> <p>$t = ? \text{ 10.1962}, x = ?$</p> <p>$x = ut + \frac{1}{2}at^2 = (50)(10.1962) = 509.81$</p>	<p>Vertical motion ($\downarrow +ve$):</p> <p>$u = 3 \text{ ms}^{-1}, a = 9.8 \text{ ms}^{-2}$,</p> <p>$t = ?$</p> <p>$y = ut + \frac{1}{2}at^2 \Rightarrow 540 = 3t + 4.9t^2$</p>		

	<ul style="list-style-type: none"> Therefore horizontal distance of package from O $= 1000 + 509.81 = 1509.81$ Therefore distance short of the drop position $= 1550 - 1509.81 = 40.19$ m 	
Q 17	<ul style="list-style-type: none"> Determine the value(s) of k for which the planes $2x + (k - 4)y + (3 - k)z = 1$, $2y + (k - 3)z = 2$, $x - 2y + z = 1$ do not intersect at a unique point: $\det \begin{vmatrix} 2 & k-4 & 3-k \\ 0 & 2 & k-3 \\ 1 & -2 & 1 \end{vmatrix} = 0 \Rightarrow k = -1, 2$ <ul style="list-style-type: none"> Test each solution. <p><u>$k = -1$</u>: $2x - 5y + 4z = 1$, $y - 2z = 1$, $x - 2y + z = 1$ Solve simultaneously (use a CAS): Infinite number of solutions which corresponds to a line.</p> <p><u>$k = 2$</u>: $2x - 2y + z = 1$, $2y - z = 2$, $x - 2y + z = 1$ Solve simultaneously (use a CAS): No solution.</p>	C

<p>Q 18</p>	<ul style="list-style-type: none"> • $\frac{x-1}{3} = \frac{3-y}{\alpha} = \frac{z+1}{4} \Rightarrow x=3t+1, y=-\alpha t+3, z=4t-1, t \in R$ <p>Therefore a vector in the direction of the line is $3\vec{i} - \alpha\vec{j} + 4\vec{k}$</p> <ul style="list-style-type: none"> • $\frac{x+1}{\beta} = \frac{y-2}{3} = \frac{z-1}{5} \Rightarrow x=\beta s-1, y=3s+2, z=5s+1, s \in R$ <p>Therefore a vector in the direction of the line is $\beta\vec{i} + 3\vec{j} + 5\vec{k}$</p> <ul style="list-style-type: none"> • Therefore a vector normal to each line is (use a CAS) is $\begin{pmatrix} 3\vec{i} - \alpha\vec{j} + 4\vec{k} \end{pmatrix} \times \begin{pmatrix} \beta\vec{i} + 3\vec{j} + 5\vec{k} \end{pmatrix} = (-12 - 5\alpha)\vec{i} + (4\beta - 15)\vec{j} + (9 + \alpha\beta)\vec{k}$ <ul style="list-style-type: none"> • Therefore $3\vec{i} - 7\vec{j} + \gamma\vec{k} = (-12 - 5\alpha)\vec{i} + (4\beta - 15)\vec{j} + (9 + \alpha\beta)\vec{k}$ <p>Equate \vec{i}-components: $3 = -12 - 5\alpha \Rightarrow \alpha = -3$</p> <p>Equate \vec{j}-components: $-7 = 4\beta - 15 \Rightarrow \beta = 2$</p> <p>Equate \vec{k}-components: $\gamma = 9 + (-3)(2) = 3$</p>	<p>D</p>
<p>Q 19</p>	<ul style="list-style-type: none"> • $sd(\bar{X}) = \frac{sd(X)}{\sqrt{n}}$. • $Var(X) = E(X^2) - (E(X))^2 = \int_0^1 x^2(2x) dx - \left(\int_0^1 x(2x) dx \right)^2 = \frac{1}{18}$ $\Rightarrow sd(X) = \frac{1}{\sqrt{18}}$ <ul style="list-style-type: none"> • $sd(\bar{X}) = \frac{sd(X)}{\sqrt{n}} = \frac{\frac{1}{\sqrt{18}}}{\sqrt{80}} = \frac{\sqrt{10}}{120}$ 	<p>C</p>

Q 20	<p>Method 1:</p> <p>Use a CAS to check the confidence interval arising from the value of n in each option: $n = 92$.</p> <p>Method 2:</p> $14572 = \bar{x} + k \frac{\sigma}{\sqrt{n}} \quad \dots (1)$ $14428 = \bar{x} - k \frac{\sigma}{\sqrt{n}} \quad \dots (2)$ $(1) + (2) \Rightarrow \bar{x} = 14500$ <p>For a 90% confidence interval: $\Pr(-k < Z < k) = 0.95 \Rightarrow k \approx 1.64485$ (use a CAS).</p> <p>Substitute $\bar{x} = 14500$, $k = 1.64485$ and $\sigma = 420$ into either equation (1) or equation (2) and solve for n (use a CAS and round to the nearest integer):</p> $n = 92.$	A
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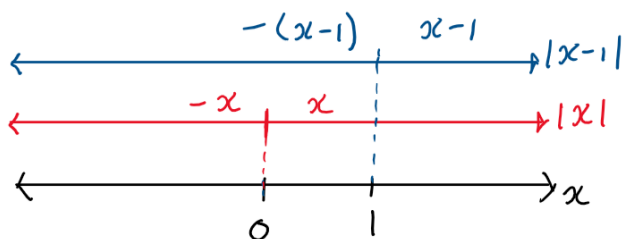
SECTION B: Solutions

Question 1

Part a.:

Note: These are only potential asymptotes because the asymptotic behaviour of f depends on the values of a and b . Some of these asymptotes do not exist for particular values of a and b (for example, f has no asymptotes when $a = 0$ and $b = -1$).

- Potential vertical asymptote: $x = 1$
- Asymptotic behaviour as $x \rightarrow \pm\infty$:



To consider $x \rightarrow +\infty$ it is therefore necessary to get the rule for $y = f(x)$ when $x \geq 1$:

$$y = f(x) = \frac{x^2 - ax + b}{x - 1} = x + 1 - a + \frac{b - a + 1}{x - 1} \quad x \rightarrow +\infty: y \sim x + 1 - a$$

Use a CAS or 'by hand'

To consider $x \rightarrow -\infty$ it is therefore necessary to get the rule for $y = f(x)$ when $x < 0$:

$$y = f(x) = \frac{x^2 - a(-x) + b}{-(x - 1)} = \frac{x^2 + ax + b}{-x + 1} = -x - 1 - a - \frac{a + b + 1}{-x + 1} \quad x \rightarrow -\infty: y \sim -x - 1 - a$$

Use a CAS or 'by hand'

<p>Three correct potential asymptotes:</p> <p>$x = 1, \quad y = x + 1 - a, \quad y = -x - 1 - a$</p> <p>Do not accept $y = x + 1 - a$ in place of $y = x + 1 - a$ and $y = -x - 1 - a$ (because $y = x + 1 - a$ is sometimes a diagonal asymptote when $y = -x - 1 - a$ is not, and vice versa).</p>	2 marks
<p>Two correct potential asymptotes.</p>	1 mark
<p>One or no correct potential asymptotes.</p>	0 marks

Part b.:

$$y = b \Rightarrow \frac{x^2 - a|x| + b}{|x-1|} = b \Rightarrow x = 0$$

For f to be 'smooth' at $x = 0$ it is necessary and sufficient that $f'(x)$ is continuous at $x = 0$

It is therefore necessary and sufficient that:

$$1. \lim_{x \rightarrow 0} f'(x) \text{ exists.} \quad 2. \lim_{x \rightarrow 0} f'(x) = f'(0)$$

$$1. \text{ Existence of } \lim_{x \rightarrow 0} f'(x)$$

From a CAS:

$$\lim_{x \rightarrow 0^+} f'(x) = b - a \quad \lim_{x \rightarrow 0^-} f'(x) = a + b$$

$$\lim_{x \rightarrow 0^+} f'(x) = \lim_{x \rightarrow 0^-} f'(x) \Rightarrow b - a = a + b \Rightarrow a = 0 \text{ and } b \in R$$

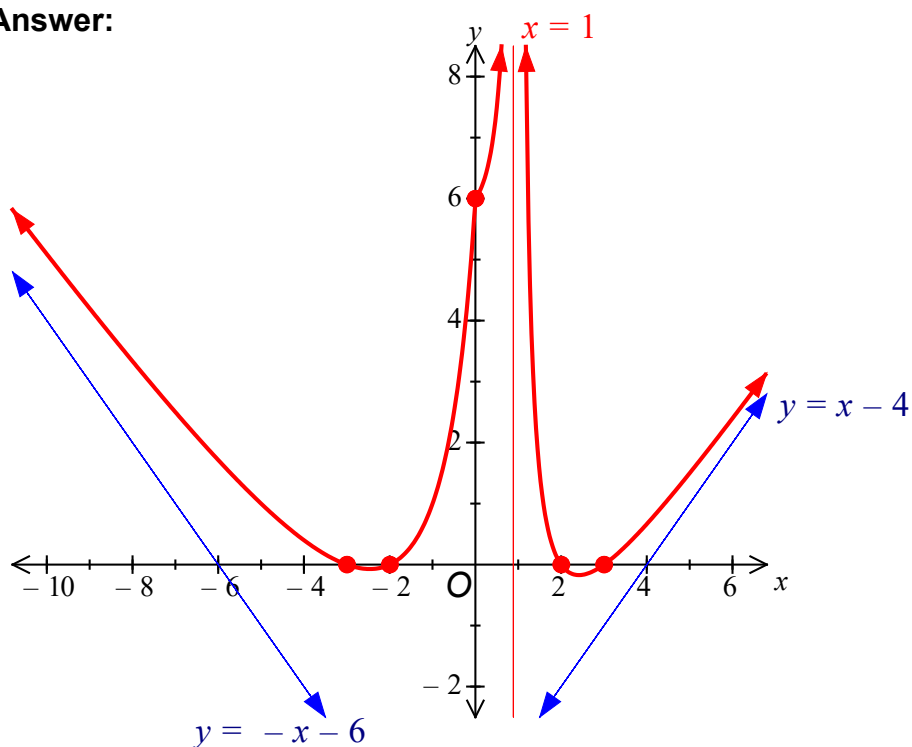
$\lim_{x \rightarrow 0^+} f'(x) = b - a$	$\lim_{x \rightarrow 0^-} f'(x) = a + b$	$a = 0 \text{ and } b \in R$	1 mark
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$$2. a = 0 \text{ and } b \in R \Rightarrow \lim_{x \rightarrow 0} f'(x) = b. \text{ It must now be checked that } f'(0) = b$$

$$a = 0 \text{ and } x \rightarrow 0 \Rightarrow x < 1 \text{ therefore } f(x) = \frac{x^2 + b}{-(x-1)} = \frac{x^2 + b}{-x + 1}$$

From a CAS: $f'(0) = b$

$\lim_{x \rightarrow 0} f'(x) = b$	$f(x) = \frac{x^2 + b}{-x + 1}$	$f'(0) = b$	1 mark
Therefore not 'smooth' at the point where $y = b$ unless $a = 0$			

Part c.:**Answer:**

Shape: There must be a 'corner' at the y-intercept. The turning point in the interval $(2, 3)$ must be lower than the turning point in the interval $(-3, -2)$.	1 mark
Asymptotes: $x = 1$, $y = x - 4$, $y = -x - 6$.	1 mark
Axis intercepts: $(2, 0)$, $(3, 0)$, $(-2, 0)$, $(-3, 0)$, $(0, 6)$.	1 mark

Calculations:

- Asymptotes are found from **Part a**.

Vertical asymptote: $x = 1$ Diagonal asymptotes: Substitute into $a = 5$ into $y = x + 1 - a$ and $y = -x - 1 - a$

- Axis intercepts:

y-intercept: Substitute $x = 0$ x-intercepts: Use a CAS to solve $\frac{x^2 - 5|x| + 6}{|x - 1|} = 0$

- Shape: From **Part b**, the graph is not smooth at $x = 0$ (that is, the y-intercept) because $a \neq 0$. Therefore there is a 'corner' at $x = 0$

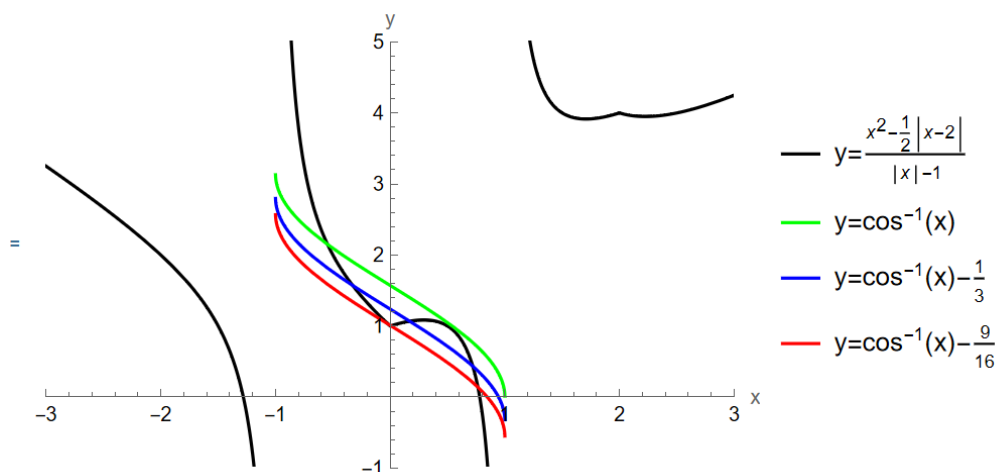
Part d.:

- $$\frac{x^2 - \frac{1}{2}|x-2|}{|x|-1} - \arccos(x) - k = 0 \quad \Rightarrow \quad \frac{x^2 - \frac{1}{2}|x-2|}{|x|-1} = \arccos(x) + k$$

- Consider the graphs of $y = f(x) = \frac{x^2 - \frac{1}{2}|x-2|}{|x|-1}$ and $y = h(x) = \arccos(x) + k$

It is required to find the values of k for which these graphs have three intersection points

The value of k controls the vertical translation of $y = \arccos(x-1) + k$:



- Minimum value of k :

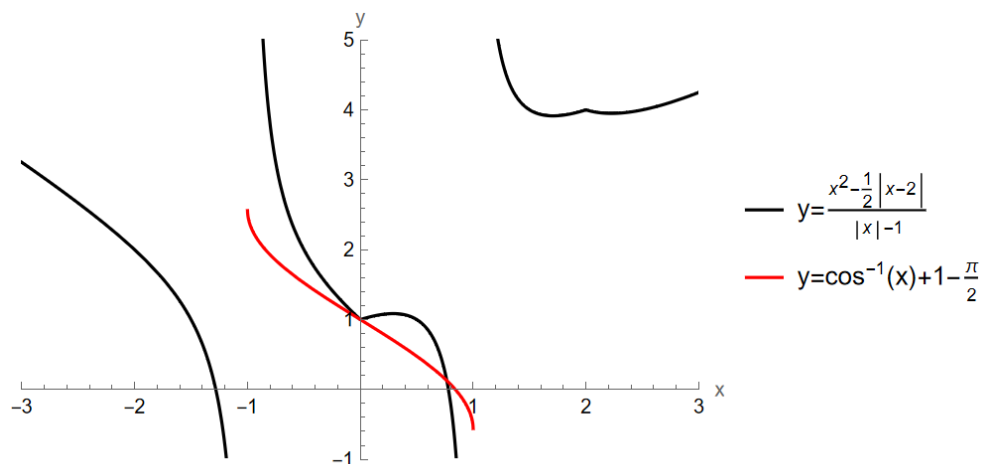
By inspection the value of k needs to be greater than the value of k such that point of

inflection of $h(x) = \arccos(x) + k$ coincides with the 'corner' of $f(x) = \frac{x^2 - \frac{1}{2}|x-2|}{|x|-1}$

at $(1, 0)$.

It is therefore required that the y -coordinate of the point of inflection of $y = \arccos(x) + k$ is equal to 1:

$$h(0) = 1: \quad \frac{\pi}{2} + k = 1 \quad \Rightarrow \quad k = 1 - \frac{\pi}{2}$$



- Maximum value of k :

By inspection there is some value $k = \alpha$ such that $f(x) = \frac{x^2 - \frac{1}{2}|x-2|}{|x|-1}$ and $h(x) = \arccos(x) + k$ have a common tangent in the interval $0 < x < 1$

There are therefore three intersection points when $1 - \frac{\pi}{2} < k \leq \alpha$

$$f(x) = \frac{2x^2 + x - 2}{2(x-1)} \text{ for } 0 < x < 1$$

Let $x = \beta$ at the point of common tangency. It is required that

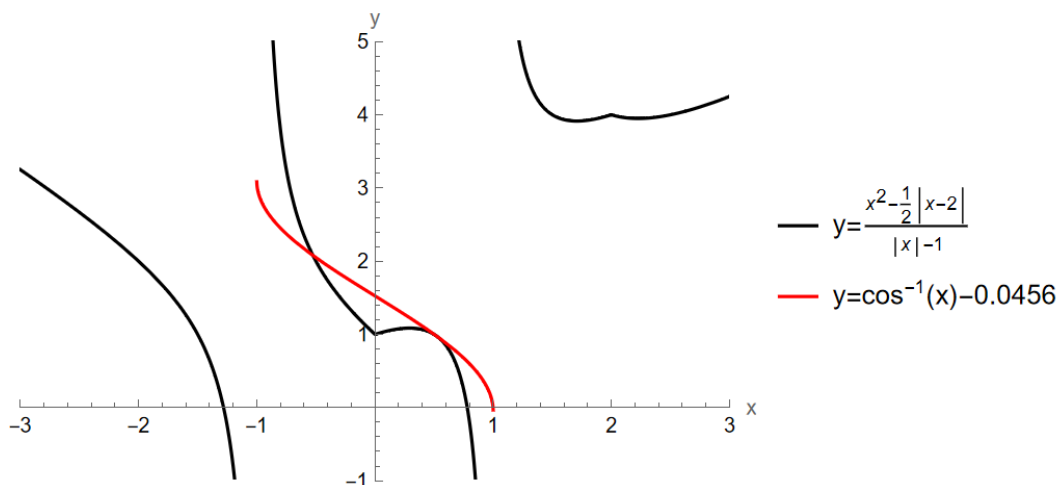
$$f(\beta) = h(\beta) \quad \dots (1)$$

$$f'(\beta) = h'(\beta) \quad \dots (2)$$

and $0 < \beta < 1$

Use a CAS to solve equations (1) and (2) simultaneously for α : $\alpha \approx -0.045612$

Note: $\beta \approx 0.520072$



$$1 - \frac{\pi}{2} < k \leq -0.0456.$$

Note:

The correct maximum value of k , rounded to four decimal places, is -0.0457 and should be accepted (rounding UP is required).

This is because $y = \arccos(x) - 0.0456$ is above $y = \frac{x^2 - \frac{1}{2}|x-2|}{|x|-1}$ on the interval $(0, 1)$

2 marks:

1 mark for the minimum value of k .

1 mark for the maximum value of k .

Question 2**Part a.:**

$|z-1|=1$ is a circle with radius $r=1$ and centre at $z=1$:

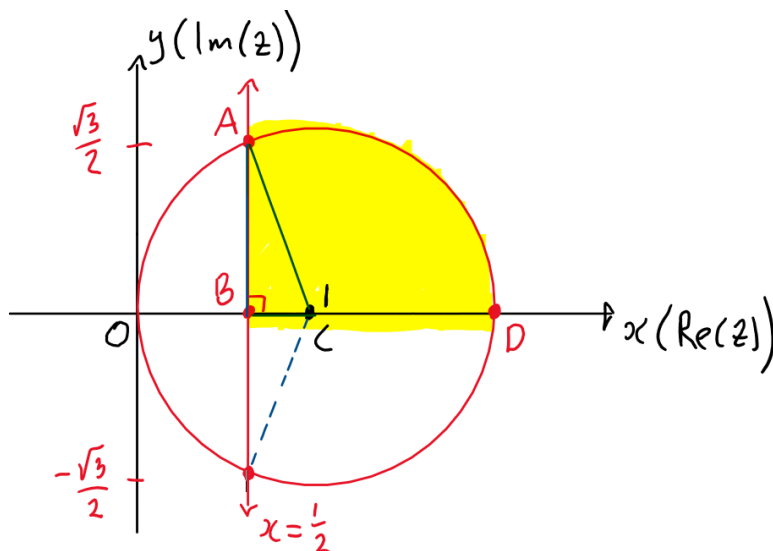
Answer: $(x-1)^2 + y^2 = 1$	1 mark
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Part b.:

- $|z|=|z-1|$ is the perpendicular bisector of the line segment joining $z=0$ and $z=1$:
 $x = \frac{1}{2}$
- Solve $(x-1)^2 + y^2 = 1$ and $x = \frac{1}{2}$ simultaneously to get coordinates of intersection points:

Answer: $\left(\frac{1}{2}, \frac{\sqrt{3}}{2}\right)$ and $\left(\frac{1}{2}, -\frac{\sqrt{3}}{2}\right)$	1 mark
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- Required area = $2(\text{Area of sector } ACD + \text{Area of triangle } ABC)$:



- Area of sector ACD :

$$\cos(\angle ACB) = \frac{BC}{AC} = \frac{1}{2} \quad \Rightarrow \angle ACB = \frac{\pi}{3} \quad \Rightarrow \angle DCB = \pi - \frac{\pi}{3} = \frac{2\pi}{3}$$

$$\text{Area of sector } ACD = \frac{1}{3} (\text{Area of circle}) = \frac{\pi}{3}$$

$r=1$

Area of sector $ACD = \frac{\pi}{3}$	1 mark
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- Area of triangle $ABC = \frac{1}{2} \left(\frac{1}{2} \right) \left(\frac{\sqrt{3}}{2} \right) = \frac{\sqrt{3}}{8}$

$$= 2 \left(\frac{\pi}{3} + \frac{\sqrt{3}}{8} \right)$$

- Required area

Answer: $\frac{2\pi}{3} + \frac{\sqrt{3}}{4}$ Accept $\frac{8\pi + 3\sqrt{3}}{12}$	1 mark
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Part c.:

- $z = 0$ is the exceptional element of $S = \{z : |z-1|=1, z \in C\}$ that is not an element of

$$\left\{ z : a\text{Arg}\left(1 - \frac{b}{z}\right) = \text{Arg}(z^2), z \in C \right\}$$

- All elements $S \setminus \{0\}$ are elements of $\left\{ z : a\text{Arg}\left(1 - \frac{b}{z}\right) = \text{Arg}(z^2), z \in C \right\}$

Therefore substitute two convenient elements of $S \setminus \{0\}$ (use the answer to **Part a.**). For example:

$$\underline{z=1+i}: a\text{Arg}\left(1 - \frac{b}{1+i}\right) = \text{Arg}\left((1+i)^2\right) \quad \dots (1)$$

$$\underline{z = \frac{1}{2} + \frac{\sqrt{3}}{2}i}: a\text{Arg}\left(1 - \frac{b}{\frac{1}{2} + \frac{\sqrt{3}}{2}i}\right) = \text{Arg}\left(\left(\frac{1}{2} + \frac{\sqrt{3}}{2}i\right)^2\right) \quad \dots (2)$$

Use a CAS to solve equations (1) and (2) simultaneously under the restriction $a, b \in R^+$:

$a = 1$ and $b = 1$.

Note: The very convenient value $z = 2$ does not give an equation that allows the unique solution for a and b .

Clear and valid method	1 mark
Answer: $a = 1$ and $b = 1$	1 mark

Part d.:

$$-\frac{\pi}{2} < \text{Arg}(z) < \frac{\pi}{2} \text{ for } z \in S = \{z : |z| = |z-1|, z \in \mathbb{C}\}$$

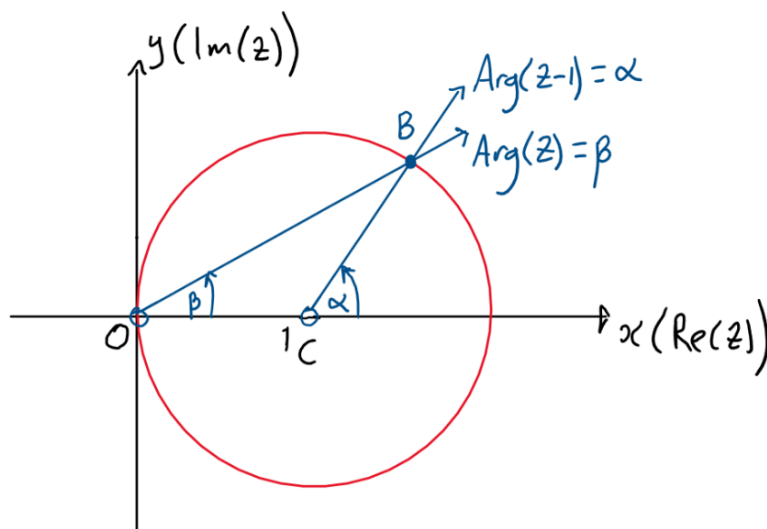
Note:

1. $z \rightarrow 0$ as $\text{Arg}(z) \rightarrow \pm \frac{\pi}{2}$ and $\text{Arg}(0)$ is not defined.
2. $\text{Arg}(z^2) = 2\text{Arg}(z)$ since $-\frac{\pi}{2} < \text{Arg}(z) < \frac{\pi}{2}$
3. $z = 0$ is the exceptional element of S that is not an element of $\{z : \text{Arg}(z-1) = \text{Arg}(z^2), z \in \mathbb{C}\}$

(because $\text{Arg}(0^2)$ is not defined).

Case 1: $z \in S \setminus \{0\}$ and $0 \leq \text{Arg}(z) < \frac{\pi}{2}$ (upper half of the circle).

Let $\text{Arg}(z-1) = \alpha$ and $\text{Arg}(z) = \beta$:



Proving $\text{Arg}(z-1) = \text{Arg}(z^2)$ is equivalent to proving $\alpha = 2\beta$:

$$OC = CB \quad (=1 = \text{radius of circle})$$

therefore $\triangle OCB$ is isosceles

$$\text{therefore } \angle BOC = \beta = \angle OBC$$

$$\text{therefore } \angle OCB = \pi - 2\beta. \quad \dots (1)$$

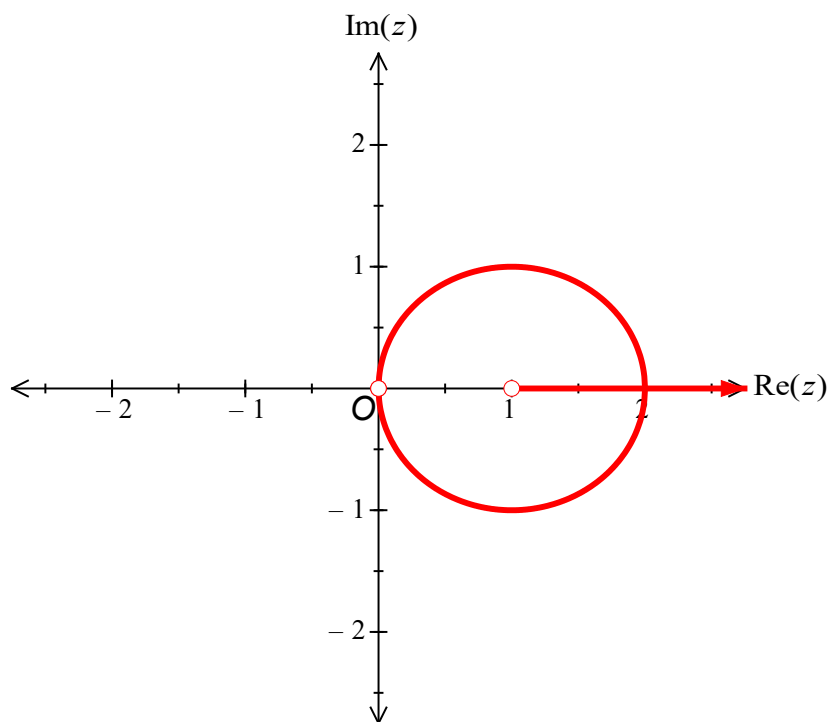
$$\text{But } \angle OCB = \pi - \alpha. \quad \dots (2)$$

$$\text{From equations (1) and (2): } \pi - 2\beta = \pi - \alpha \quad \Rightarrow 2\beta = \alpha \quad \blacksquare$$

Case 2: $z \in S \setminus \{0\}$ and $-\frac{\pi}{2} < \text{Arg}(z) \leq 0$ (lower half of the circle).

The proof is identical to **Case 1** by symmetry.

$\text{Arg}(z^2) = 2\text{Arg}(z)$ since $-\frac{\pi}{2} < \text{Arg}(z) < \frac{\pi}{2}$ $z = 0$ is the exceptional element of S that is not an element of $\{z : \text{Arg}(z-1) = \text{Arg}(z^2), z \in C\}$	1 mark
Appropriate labelled diagram. Geometric proof.	1 mark

Part e.:**Answer:**

Shape: Circle $ z-1 =1$ with 'hole' at $z=0$	1 mark
Shape: Ray with terminus at $z=1$	1 mark
'Hole' at terminus of ray.	1 mark

Calculations:**Shape:**

- From **part d.** it is known that the circle $|z-1|=1$, $z \neq 0$, is part of the solution.
- From **part d.** it is seen that $\text{Arg}(z-1)$ and $\text{Arg}(z^2)$ are equal when z is real and $z > 1$ ($\alpha = \beta = 0$)

Alternatively, $\text{Arg}(z-1) = \text{Arg}(z^2)$ when $z > 1$ can be seen by inspection. If z is real:

$$z^2 > 0 \text{ therefore } \text{Arg}(z^2) = 0$$

$$z > 1 \Rightarrow z-1 > 0 \text{ therefore } \text{Arg}(z-1) = 0 \text{ therefore } \text{Arg}(z-1) = \text{Arg}(z^2)$$

$$z < 1 \Rightarrow z-1 < 0 \text{ therefore } \text{Arg}(z-1) = \pi \text{ therefore } \text{Arg}(z-1) \neq \text{Arg}(z^2)$$

$\text{Arg}(z-1)$ is not defined for $z=1$ therefore $z=1$ is not a solution to $\text{Arg}(z-1) = \text{Arg}(z^2)$

Part f.:

Let $\text{Arg}(z-1) = \alpha$ and $\text{Arg}(z) = \beta$ where $\alpha = 2\beta$ (from **Part d.**).

- $\text{Arg}(z^2) = 2\text{Arg}(z)$

$$\text{since } z \in S \text{ and } -\frac{\pi}{2} < \text{Arg}(z) < \frac{\pi}{2} \text{ for } S$$

$$= 2\beta$$

- $\text{Arg}(z^2 - z) = \text{Arg}(z(z-1)) = \text{Arg}(z) + \text{Arg}(z-1) = \beta + \alpha = \beta + 2\beta = 3\beta$

provided

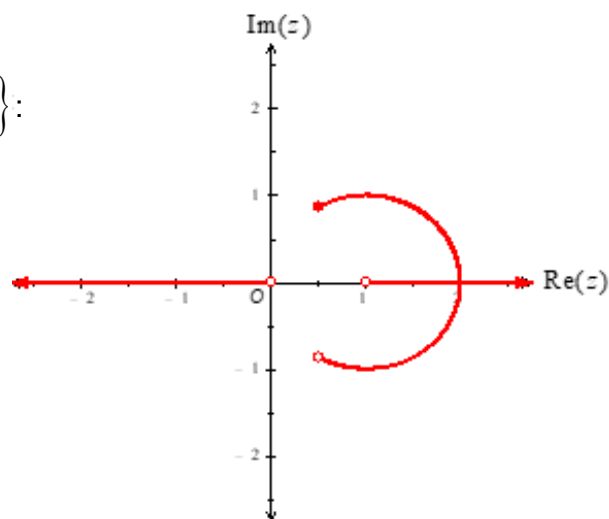
$$-\pi < 3\beta \leq \pi \quad \Rightarrow \quad -\frac{\pi}{3} < \beta \leq \frac{\pi}{3}$$

Then $3\text{Arg}(z^2) = 2\text{Arg}(z^2 - z) \quad \Rightarrow \quad 3(2\beta) = 2(3\beta) \quad \checkmark$

Recognition that $\text{Arg}(z^2 - z) = \text{Arg}(z) + \text{Arg}(z-1)$ provided $-\pi < \text{Arg}(z) + \text{Arg}(z-1) \leq \pi$	1 mark
Answer: $-\frac{\pi}{3} < \text{Arg}(z) \leq \frac{\pi}{3}$	1 mark

Discussion:

Sketch of $\{z : 3\text{Arg}(z^2) = 2\text{Arg}(z^2 - z), z \in \mathbb{C}\}$:

**Calculations:**

- It is known that the circle $|z-1|=1$ is part of the solution for $-\frac{\pi}{3} < \text{Arg}(z) \leq \frac{\pi}{3}$
- It is seen by inspection that $3\text{Arg}(z^2)$ and $2\text{Arg}(z^2 - z)$ are equal when z is real and $z^2 > 0$ and $z^2 - z > 0$:

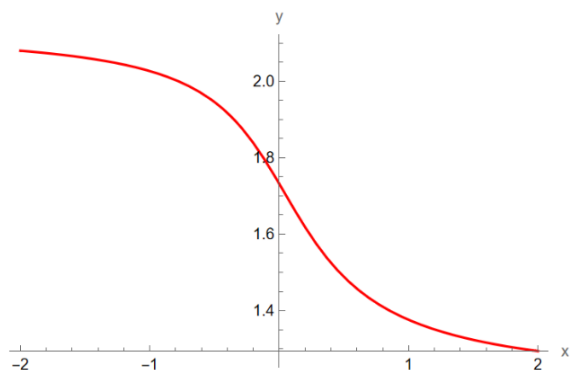
$$z < 0 \text{ or } z > 1$$

Note: If z is real:

$z^2 > 0$ therefore $\text{Arg}(z^2) = 0$

- $z > 1 \Rightarrow z^2 - z > 0$ therefore $\text{Arg}(z^2 - z) = 0$ therefore $3\text{Arg}(z^2) = 2\text{Arg}(z^2 - z)$
- $0 < z < 1 \Rightarrow z^2 - z < 0$ therefore $\text{Arg}(z^2 - z) = \pi$ therefore $3\text{Arg}(z^2) \neq 2\text{Arg}(z^2 - z)$
- $z < -1 \Rightarrow z^2 - z > 0$ therefore $\text{Arg}(z^2 - z) = 0$ therefore $3\text{Arg}(z^2) = 2\text{Arg}(z^2 - z)$

Question 3



Part a.:

$V = \pi \int_0^1 \left(3 - \frac{1}{4} \tan^{-1} \left(\frac{2x}{y} \right) \right)^2 dx$	<p>1 mark</p>
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<p>Answer: 7.2106 cubic units</p>	<p>1 mark</p>
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Part b.:**Integral terminals:**

<ul style="list-style-type: none"> $x = -1 \Rightarrow y = \sqrt{3 - \tan^{-1}(-2)}$. Accept $y = \sqrt{3 + \tan^{-1}(2)}$ $x = 0 \Rightarrow y = \sqrt{3}$ 	1 mark
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$S = 2\pi \int_{\sqrt{3}}^{\sqrt{3 - \tan^{-1}(-2)}} x \sqrt{1 + \left(\frac{dx}{dy}\right)^2} dy \quad \text{or} \quad S = 2\pi \int_{\sqrt{3}}^{\sqrt{3 + \tan^{-1}(2)}} x \sqrt{1 + \left(\frac{dx}{dy}\right)^2} dy$ <p>Accept $S = -2\pi \int_{\sqrt{3 - \tan^{-1}(-2)}}^{\sqrt{3}} x \sqrt{1 + \left(\frac{dx}{dy}\right)^2} dy, \quad S = 2\pi \left \int_{\sqrt{3 - \tan^{-1}(-2)}}^{\sqrt{3}} x \sqrt{1 + \left(\frac{dx}{dy}\right)^2} dy \right \text{ etc}$</p>	1 mark Order of terminals must be correct.
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- Substitute $x = \frac{1}{2} \tan(3 - y^2)$:

Answer: 3.2253 square units.	1 mark
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Part c.:

$L = \pi \int_{-1}^1 \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$	1 mark
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Answer: 2.1233 units.	1 mark
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Part d.:

Use $S = 2\pi \int_a^b y \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$:

- $S_f = 2\pi \int_a^b f(x) \sqrt{1 + (f'(x))^2} dx$
- $S_g = 2\pi \int_a^b g(x) \sqrt{1 + (g'(x))^2} dx$

$S_g = 2\pi \int_a^b (f(x) + k) \sqrt{1 + (f'(x))^2} dx$	1 mark
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$$= 2\pi \int_a^b f(x) \sqrt{1 + (f'(x))^2} dx + 2\pi \int_a^b k \sqrt{1 + (f'(x))^2} dx$$

$$= 2\pi \int_a^b f(x) \sqrt{1 + (f'(x))^2} dx + 2\pi k \int_a^b \sqrt{1 + (f'(x))^2} dx$$

$\frac{1}{L} \quad 4 \quad 44 \quad 2 \quad 4 \quad 4 \quad 4 \quad 4$

Answer: $S_g = S_f + 2\pi kL$	1 mark
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Question 4

Part a.:

Require $\frac{dN}{dt} > 0$ at $t=0$, that is, when $N = 150$: $2(150) \left(1 - \frac{150}{600}\right) - n > 0$

Answer: $0 < n < 225$	1 mark
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Part b.:

$$\frac{dN}{dt} = 2N \left(1 - \frac{N}{600} \right) - n \quad \Rightarrow \quad \frac{dt}{dN} = \frac{1}{2N \left(1 - \frac{N}{600} \right) - n} = \frac{1}{\frac{-N^2}{300} + 2N - n}$$

Require $\frac{-N^2}{300} + 2N - n$ to be a perfect square.	1 mark
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Therefore $\Delta = (2)^2 - 4 \left(\frac{-1}{300} \right) (-n) = 0$.

Answer: $n = 300$	1 mark
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Check (use a CAS):

Solve $\frac{dN}{dt} = 2N \left(1 - \frac{N}{600} \right) - 300$ with initial condition $N(0) = 150$:

$$N = \frac{300(t-1)}{t-2} = 300 + \frac{300}{t-2}.$$

Observation: $N = 0$ when $t = 1$.

Part c.:

Use a CAS to solve $\frac{dN}{dt} = 2N\left(1 - \frac{N}{600}\right) - n$ with initial condition $N(0) = 150$:

$$N = 300 - 10\sqrt{3}\sqrt{n-300} \tan\left(\frac{\sqrt{n-300}}{10\sqrt{3}}t + \tan^{-1}\left(\frac{5\sqrt{3}}{\sqrt{n-300}}\right)\right)$$

Note: Different CAS may give different but equivalent forms.

Substitute $t = 4$ and solve $N = 0$ for n (round to the nearest integer):

$300 - 10\sqrt{3}\sqrt{n-300} \tan\left(\frac{4\sqrt{n-300}}{10\sqrt{3}} + \tan^{-1}\left(\frac{5\sqrt{3}}{\sqrt{n-300}}\right)\right) = 0$	1 mark
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Answer: $n = 227$	1 mark
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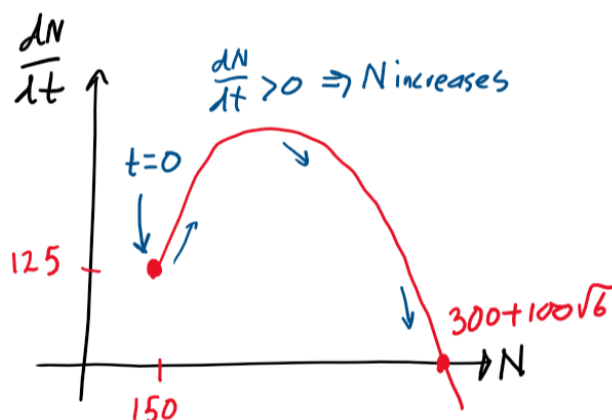
Check (use a CAS):

- Solve $\frac{dN}{dt} = 2N\left(1 - \frac{N}{600}\right) - 227$ with initial condition $N(0) = 150$
- Substitute $N = 0$ and solve for t : $t = 3.96966$ ✓

Part d. i.:

$$\frac{dN}{dt} = 2N \left(1 - \frac{N}{600} \right) - 100 \text{ with initial condition } N(0) = 150$$

Phase diagram (plot of $\frac{dN}{dt}$ versus N):



$\frac{dN}{dt} > 0$ at $t=0$ ($N=150$) therefore N initially increases.

$\frac{dN}{dt} > 0$ as N increases ($t > 0$) therefore N continues to increase.

$N \rightarrow 300 + 100\sqrt{6}$ as $\frac{dN}{dt} \rightarrow 0$.

<p>Valid explanation that refers to a phase diagram.</p> <p>$N \rightarrow 300 + 100\sqrt{6}$</p>	1 mark
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<p>Answer: 545</p>	1 mark
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Check (use a CAS):

- Solve $\frac{dN}{dt} = 2N \left(1 - \frac{N}{600} \right) - 100$ with initial condition $N(0) = 150$
- Calculate $\lim_{t \rightarrow +\infty} N(t)$: $300 + 100\sqrt{6}$

Part d. ii.:

$\frac{dN}{dt} = 2N\left(1 - \frac{N}{600}\right) - 100$ has a turning point at $N = 300$ therefore there is a point of inflection at $N = 300$

Answer: $N = 300$	1 mark
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Check (use a CAS):

- Solve $\frac{dN}{dt} = 2N\left(1 - \frac{N}{600}\right) - 100$ with initial condition $N(0) = 150$
- Solve $\frac{d^2N}{dt^2} = 0$ for t : $t = \frac{1}{2} \frac{\sqrt{3}}{2} \log_e \left(\frac{4 + \sqrt{6}}{4 - \sqrt{6}} \right)$
- Substitute $t = \frac{1}{2} \frac{\sqrt{3}}{2} \log_e \left(\frac{4 + \sqrt{6}}{4 - \sqrt{6}} \right)$ into N : $N = 300$

Part e.:

- Use a CAS to solve $\frac{dN}{dt} = 2N\left(1 - \frac{N}{600}\right) - 100$ with initial condition $N(0) = 150$
- Substitute $N = 400$ and solve for t (round to two decimal places):

Answer: $t = 1.40$	1 mark
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Question 5**Part a.:**

If \vec{v} and \vec{w} are normal to each other then $\vec{v} \cdot \vec{w} = 0$:

$\left(\begin{matrix} -1 \\ -2 \\ 1 \end{matrix} \right) \cdot \left(\begin{matrix} 3 \\ -2 \\ -1 \end{matrix} \right) = -3 + 4 - 1 = 0$	<p>1 mark</p> <p>Explicit calculation is required.</p>
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Part b.:**Method 1:**

- A cartesian equation of the plane is $ax + by + cz = d$ where $\vec{n} = a\vec{i} + b\vec{j} + c\vec{k}$ is a vector normal to the plane.

A normal vector to the plane is $\vec{n} = \vec{v} \times \vec{w}$. From a CAS or 'by hand':

$$\vec{v} \times \vec{w} = 4\vec{i} + 2\vec{j} + 8\vec{k}$$

<p>Normal vector: $4\vec{i} + 2\vec{j} + 8\vec{k}$</p>	<p>1 mark</p>
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- Therefore $4x + 2y + 8z = d$

Substitute the point $(2, -2, -1)$ into $4x + 2y + 8z = d$ and solve for d : $d = -4$

Therefore $4x + 2y + 8z = -4$

<ul style="list-style-type: none"> Explicit solution for d using the point $(2, -2, -1)$ Answer: $2x + y + 4z = -2$ 	<p>1 mark</p> <p>Accept all equivalent answers.</p>
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Method 2:

- $(2, -2, -1)$ is a point contained in the plane Π and the vectors \vec{v} and \vec{w} are parallel to Π

Therefore a vector equation of Π is $\vec{r}_\Pi = 2\vec{i} - 2\vec{j} - \vec{k} + \lambda\vec{v} + \mu\vec{w}$ where $\lambda \in \mathbb{R}$ and $\mu \in \mathbb{R}$

Therefore a set of parametric equations defining Π is

$x = 2 - \lambda + 3\mu$ (1)	1 mark
$y = -2 - 2\lambda - 2\mu$ (2)	
$z = -1 + \lambda - \mu$ (3)	

- Use a CAS to solve equations (1), (2) and (3) simultaneously for λ , μ and one of either x , y or z and simplify the 'cartesian' solution.

(This is equivalent to solving two of the equations simultaneously for λ and μ in terms of x , y and z and then substituting those solutions into the third equation).

Answer: $2x + y + 4z = -2$	1 mark
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Part c.:

From the answer to **Part b.**, it is noted that the point $(4, 2, -3)$ is contained in the plane Π .

The vectors \vec{v} and \vec{w} are parallel to Π .

Therefore a vector equation of Π is

$\vec{r}_{\Pi} = 4\vec{i} + 2\vec{j} - 3\vec{k} + \lambda\vec{v} + \mu\vec{w} \text{ where } \lambda \in \mathbb{R} \text{ and } \mu \in \mathbb{R}$	<p>1 mark</p> <ul style="list-style-type: none"> • Symbols different to \vec{r} and t must be used in the vector equation. • Parameters must be explicitly defined.
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Note:

- A symbol different to \vec{r} must be used in the vector equation of Π because \vec{r} is the position vector of the object.
- A symbol different to t (such as λ) must be used to represent a parameter in the vector equation of Π because t represents time in the position vector of the object.

<p>Choosing $\lambda = \cos(2t)$ and $\mu = \sin(3t)$ in $\vec{r}_{\Pi} = 4\vec{i} + 2\vec{j} - 3\vec{k} + \lambda\vec{v} + \mu\vec{w}$ defines the position vector of the object.</p> <p>Therefore the points on the path followed by the object are a subset of the points contained in the plane.</p>	<p>1 mark</p>
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Part d.:

- $\vec{r}_\Pi = 4\vec{i} + 2\vec{j} - 3\vec{k} + \cos(2t)|\vec{v}| \hat{v} + \sin(3t)|\vec{w}| \hat{w}$ (from **part c.**).
- Since \vec{v} and \vec{w} are perpendicular to each other (from **part a.**), the unit vectors \hat{v} and \hat{w} parallel to the plane Π are analogous to the unit vectors \vec{i} and \vec{j} parallel to the xy -plane.
- Therefore the parametric equations defining the path followed by the object in the plane Π are equivalent to the parametric equations

$$x = |\vec{v}| \cos(2t) = \sqrt{6} \cos(2t), \quad y = |\vec{w}| \sin(3t) = \sqrt{14} \sin(3t)$$

in the xy -plane.

$x = \sqrt{6} \cos(2t), \quad y = \sqrt{14} \sin(3t)$	1 mark
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- Substitute $x = \sqrt{6} \cos(2t)$, $y = \sqrt{14} \sin(3t)$, $t_1 = 0$ and $t_2 = 1$

into the arc length parametric formula $\int_{t_1}^{t_2} \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$ and evaluate using a CAS:

Answer: 8.24	1 mark
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Part e.:

$\vec{s} = \vec{i} + \vec{j} + 6\vec{k} + t(\vec{-i} + 6\vec{j} - \vec{k})$ is the vector equation of a line.

By inspection a set of parametric equations defining the line is

$$x = 1 - t \quad \Rightarrow t = -x + 1 \quad \dots (1)$$

$$y = 1 + 6t \quad \Rightarrow t = \frac{y-1}{6} \quad \dots (2)$$

$$z = 6 - t \quad \Rightarrow t = -z + 6 \quad \dots (3)$$

Equate equations (1), (2) and (3):

<p>Answer: $-x + 1 = \frac{y-1}{6} = -z + 6$</p> <p>Accept all equivalent forms.</p>	<p>1 mark</p>
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Part f.:

- It is prudent to check whether or not the line intersects the plane Π (if the line intersects the plane then the distance is equal to zero).

Method 1:

Substitute the parametric equations

$$x = 1 - t, \quad y = 1 + 6t, \quad z = 6 - t$$

of the line into the equation $2x + y + 4z = -2$ of Π (from **part b.**) and solve for t :

$$2(1-t) + (1+6t) + 4(6-t) = -2 \quad \Rightarrow 27 = -2$$

which is inconsistent. Therefore the line does not intersect Π .

Method 2: Determine whether or not the line is parallel to Π .

A vector in the direction of the line is $-\vec{i} + 6\vec{j} - \vec{k}$ (by inspection) and a normal vector to the plane is $4\vec{i} + 2\vec{j} + 8\vec{k}$ (from **part b.**).

$$\left(-\vec{i} + 6\vec{j} - \vec{k}\right) \cdot \left(4\vec{i} + 2\vec{j} + 8\vec{k}\right) = 0 \text{ therefore the line is parallel to the plane.}$$

Note: The line does not lie in Π since any chosen point on the line does not satisfy the equation of the plane.

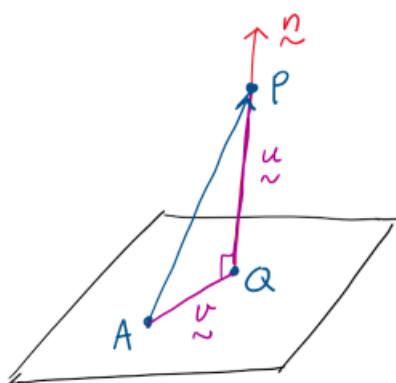
- Calculate the distance.

Note: Since the question is worth 2 marks, “appropriate working **must** be shown”.

Method	Example calculation
<ul style="list-style-type: none"> • Calculate the distance from Π of any chosen point P on the line. 	Choose $P(1, 1, 6)$ (corresponding to $t = 0$).
<ul style="list-style-type: none"> • Define the position vector of P. 	$\vec{OP} = \vec{i} + \vec{j} + 6\vec{k}$.
<ul style="list-style-type: none"> • Get a normal vector \vec{n} to Π. 	$\vec{n} = 4\vec{i} + 2\vec{j} + 8\vec{k}$ (from part b.)
<ul style="list-style-type: none"> • Apply the distance formula $\frac{ \vec{n} \cdot \vec{OP} - d }{ \vec{n} }$ where d is found from the cartesian equation $ax + by + cz = d$ of Π. 	<p>From either a CAS or ‘by hand’:</p> $\frac{\left \left(4\vec{i} + 2\vec{j} + 8\vec{k}\right) \cdot \left(\vec{i} + \vec{j} + 6\vec{k}\right) - (-2) \right }{ 4\vec{i} + 2\vec{j} + 8\vec{k} } = \frac{4\sqrt{7}}{\sqrt{3}}.$ <p>Note: $d = -2$ comes from $2x + y + 4z = -2$ (from part b.)</p>

<p>Application of $\frac{ \vec{n} \cdot \vec{OP} - d }{ \vec{n} }$ or any other valid method.</p>	<p>1 mark</p>
<p>Answer: $\frac{4\sqrt{21}}{3}$</p>	<p>1 mark</p>

Derivation of distance formula:



$$\begin{aligned}
 |\vec{PQ}| &= |\text{scalar resolute of } \vec{AP} \text{ in the direction of } \vec{n}| \\
 &= \frac{|\vec{AP} \cdot \vec{n}|}{|\vec{n}|} = \frac{|(-\vec{OA} + \vec{OP}) \cdot \vec{n}|}{|\vec{n}|} \\
 &= \frac{|\vec{n} \cdot \vec{OP} - \vec{n} \cdot \vec{OA}|}{|\vec{n}|} \\
 &= \frac{|\vec{n} \cdot \vec{OP} - d|}{|\vec{n}|}
 \end{aligned}$$

$$\vec{n} \cdot \vec{OA} = d:$$

From the vector eqⁿ of a plane: $\vec{r} \cdot \vec{n} = \vec{OA} \cdot \vec{n}$

$$\Rightarrow ax + by + cz = \vec{OA} \cdot \vec{n}$$

$$\Rightarrow d = \vec{OA} \cdot \vec{n}$$

Question 6**Part a.:**

- Let X be the random variable “Amount of manure (kg) in a small bag”:

$$X \sim \text{Normal}(\mu_X, \sigma_X = 0.75)$$

- Let the random variable $W = X_1 + X_2 + X_3$

where X_1 , X_2 and X_3 are independent copies of X :

$$\mu_W = \mu_{X_1} + \mu_{X_2} + \mu_{X_3} = 3\mu_X$$

$$\sigma_W^2 = 1^2 \sigma_{X_1}^2 + 1^2 \sigma_{X_2}^2 + 1^2 \sigma_{X_3}^2 = 3\sigma_X^2 = 3(0.75)^2 \text{ therefore } \sigma_W = 0.75\sqrt{3}$$

W follows a normal distribution since X_1 , X_2 and X_3 are independent normal random variables.

Definition of appropriate random variables. $W \sim \text{Normal}(3\mu_X, \sigma_W = 0.75\sqrt{3})$	1 mark
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- $\Pr(W > 46) = 0.6239$.

$$Z = \frac{W - \mu_W}{\sigma_W} \Rightarrow z = \frac{46 - 3\mu_X}{0.75\sqrt{3}} \text{ where } \Pr(Z > z) = 0.6239 \Rightarrow z = -0.31574$$

$\frac{46 - 3\mu_X}{0.75\sqrt{3}} = -0.31574$	1 mark Give 1 mark if z-value is wrong but do not give the answer mark.
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- Use a CAS to solve for μ_X : $\mu_X \approx 15.4701$

Answer: $\mu_X = 15.47$	1 mark There must be evidence that Z was used.
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Rounding check: $\mu_X = 15.47 \Rightarrow \Pr(W > 46) = 0.62385 \approx 0.6239$ ✓

Part b.:

The statistical test is applied at the 3% level of significance therefore the probability of a type I error is $\frac{3}{100} = 0.03$

<p>Answers:</p> <ul style="list-style-type: none"> • $H_0: \mu = 25$ • $H_1: \mu \neq 25$ • 0.03 	1 mark
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Part c.:

- $\bar{x} = \frac{807.4}{32} = 25.23125$
- **Two-sided test** therefore $p = 2 \Pr(\bar{X} > 25.23125 | H_0 \text{ true})$.

Under H_0 : $\bar{X} \sim \text{Normal}\left(\mu_{\bar{X}} = \mu_X = 25, \sigma_{\bar{X}} = \frac{\sigma_X}{\sqrt{n}} = \frac{1}{\sqrt{32}}\right)$

Therefore:

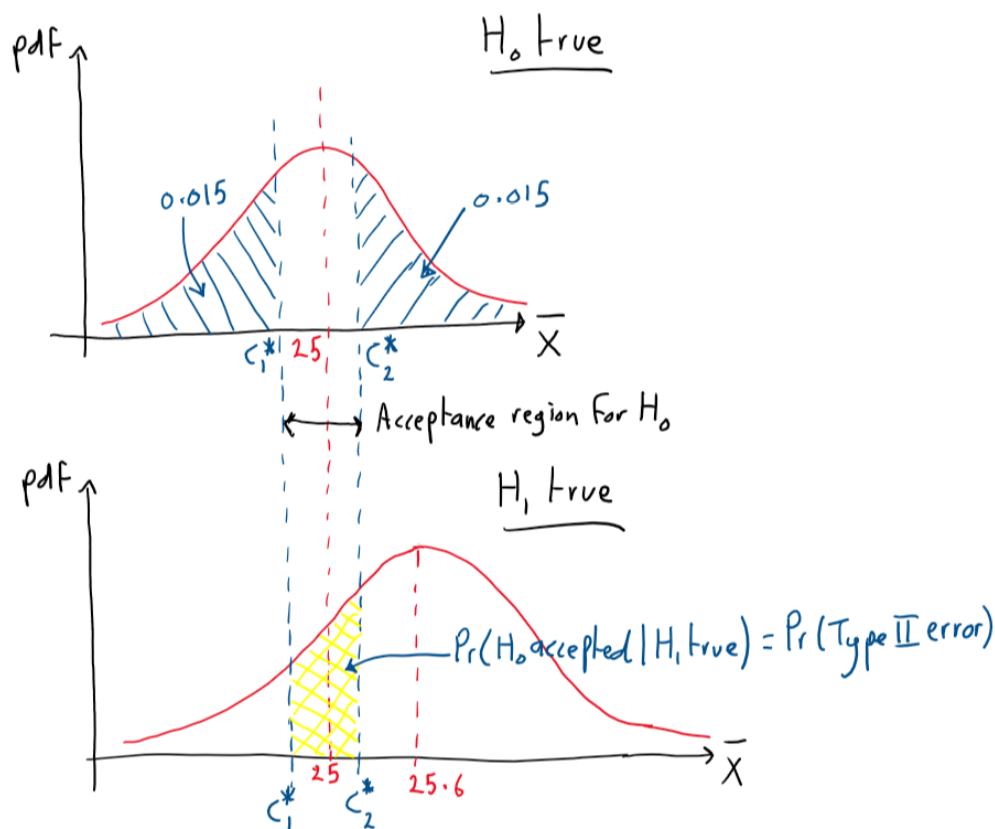
$p = 2 \Pr\left(\bar{X} > 25.23125 \mid \bar{X} \sim \text{Normal}\left(\mu_{\bar{X}} = 25, \sigma_{\bar{X}} = \frac{1}{\sqrt{32}}\right)\right)$ <p style="color: red; text-align: center;">Accept all equivalent statements such as</p> $p = \Pr\left(\left \bar{X} - 25\right > 0.23125 \mid \bar{X} \sim \text{Normal}\left(\mu_{\bar{X}} = 25, \sigma_{\bar{X}} = \frac{1}{\sqrt{32}}\right)\right)$	1 mark
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- From a CAS:

Answer: 0.0954	1 mark
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Part d.:

- Definition: A type II error is the failure to reject H_0 when H_0 is false.
- Critical values C_1^* and C_2^* of \bar{X} (use a CAS):

**Note 1:**

C_1^* and C_2^* are symmetric about $\mu_{\bar{X}} = 25$ by symmetry of the normal distribution.

Note 2:

The interval (C_1^*, C_2^*) is **not** a confidence interval. It is the acceptance region for H_0

- H_0 is accepted when $\bar{x} \in (C_1^*, C_2^*)$

Option 1:

$$\Pr(\bar{X} > C_2^*) = \frac{1}{2}(0.03) = 0.015 \Rightarrow C_2^* = 25.3836214. \quad \Pr(\bar{X} < C_1^*) = 0.015 \Rightarrow C_1^* = 24.61637859.$$

Option 2:

$$\Pr(25 - k < \bar{X} < 25 + k) = 0.97 \Rightarrow k = 0.383621 \quad C_1^* = 25 - k \text{ and } C_2^* = 25 + k$$

A correct critical value: Either $C_1^* = 24.61637859$ or $C_2^* = 25.3836214$	1 mark More than three decimal place accuracy is required (to avoid rounding error in final answer)
Statement of probability of type II error using critical values: $\Pr(C_1^* < \bar{X} < C_2^* \mu_{\bar{X}} = 25.6)$	1 mark
Answer: 0.110	1 mark